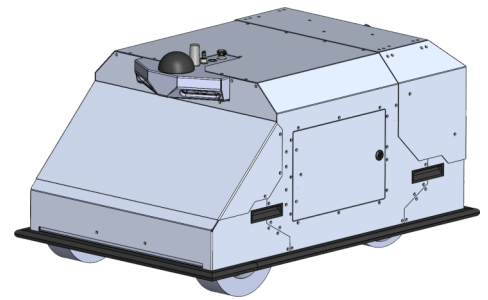# Angsa Robotics
Software Engineering Positions

Working Student   **Practical / IDP**   **Thesis**

Angsa revolutionizes the removal of trash on grass and gravel: Individual objects are detected by an artificial intelligence and removed by the autonomous robot.

Who we are Looking for

- You like solving complex problems!
- Proficiency in Python and/or C++
- Structured coding style & teamwork
- Experience form previous projects

Tasks and Projects change rapidly at Angsa. Let's get in touch and talk about the options.

Possible Tasks

- **Data Science:** Data processing & management, 3D vision, Deep Learning
- **Low Level:** CAN motor and sensor access, low level hardware control
- **Navigation:** ROS2 Module implementation, deployment tests & automation
- **Web:** Deployment App, Dashboard, Remote Monitoring

Startup-Culture
Team events, agile work style, flat hierarchies and flexible working hours.

Real-World Impact
You are part of the world's first trash picking robot, used by real customers.

Ownership
You get resposibility for your module. You can shape your role in the team.

In the Heart of Munich
We work in the Munich Urban Colab. Access to the Makerspace, Coffee & Snacks.

Sounds Interesting? Questions?

Call us or send us your profile via mail.
You can also visit us our office in the Munich Urban Colab, near the Hochschule (ask at the front desk).

Find us in the city center:
Munich Urban Colab

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ANGSA